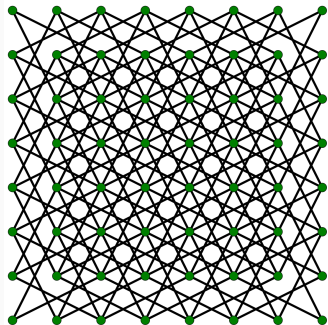


## Games, graphs, and machines

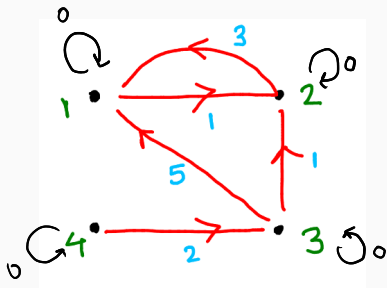


← ?  
Graph of  
Knight  
moves.

# Min/plus powers = least costly paths

## Theorem

Let  $A$  be the min/plus adjacency matrix of a graph. Then  $A_{i,j}^{\odot n}$  is the cost of the least costly path of length  $n$  from  $i$  to  $j$ .



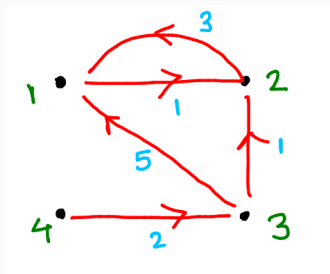
$$A = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 5 & 1 & 0 & \infty \\ \infty & \infty & 2 & 0 \end{pmatrix}$$

(and loops of cost 0)

# Min/plus powers = least costly paths

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Let  $A$  be the min/plus adjacency matrix of a graph. Then  $A_{ij}^{\odot n}$  is the cost of the least costly path of length  $n$  from  $i$  to  $j$ .



(and loops of cost 0)

$$A^1 = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 5 & 1 & 0 & \infty \\ \infty & \infty & 2 & 0 \end{pmatrix}$$

direct  
flights

len 2 paths

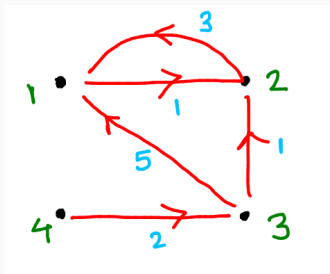
$$A^{\odot 2} = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 4 & 1 & \infty & \infty \\ 7 & 3 & 2 & 0 \end{pmatrix}$$

2 leg  
flights

# Min/plus powers = least costly paths

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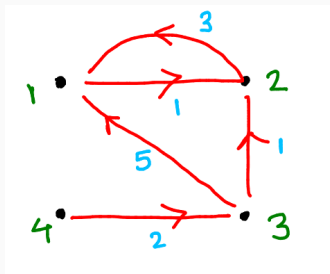
$$A = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 5 & 1 & 0 & \infty \\ \infty & \infty & 2 & 0 \end{pmatrix}$$

$$A^{\odot 3} = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 4 & 1 & 0 & \infty \\ 6 & 3 & 2 & 0 \end{pmatrix}$$

# Min/plus powers = least costly paths

## Theorem

Let  $A$  be the min/plus adjacency matrix of a graph. Then  $A_{ij}^{\odot n}$  is the cost of the least costly path of length  $n$  from  $i$  to  $j$ .



(and loops of cost 0)

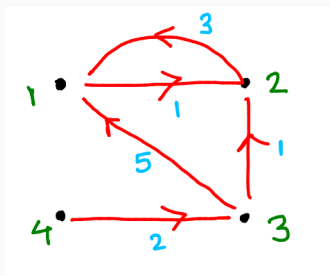
$$A = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 5 & 1 & 0 & \infty \\ \infty & \infty & 2 & 0 \end{pmatrix}$$

$$A^{\odot 4} = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 4 & 1 & \infty & \infty \\ 6 & 3 & 2 & 0 \end{pmatrix}$$

# Min/plus powers = least costly paths

## Theorem

Let  $A$  be the min/plus adjacency matrix of a graph. Then  $A_{ij}^{\odot n}$  is the cost of the least costly path of length  $n$  from  $i$  to  $j$ .



(and loops of cost 0)

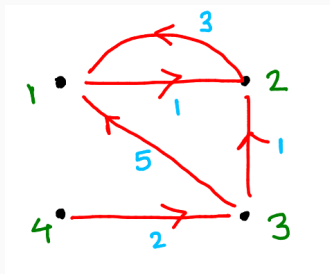
$$A = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 5 & 1 & 0 & \infty \\ \infty & \infty & 2 & 0 \end{pmatrix}$$

$$A^{\odot 5} = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 4 & 1 & \infty & \infty \\ 6 & 3 & 2 & 0 \end{pmatrix}$$

# Min/plus powers = least costly paths

## Theorem

Let  $A$  be the min/plus adjacency matrix of a graph. Then  $A_{ij}^{\odot n}$  is the cost of the least costly path of length  $n$  from  $i$  to  $j$ .



(and loops of cost 0)

$$A = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 5 & 1 & 0 & \infty \\ \infty & \infty & 2 & 0 \end{pmatrix}$$

$$A^{\odot n} = \begin{pmatrix} 0 & 1 & \infty & \infty \\ 3 & 0 & \infty & \infty \\ 4 & 1 & \infty & \infty \\ 6 & 3 & 2 & 0 \end{pmatrix}$$

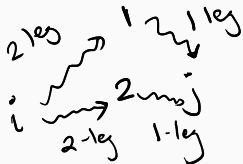
$n \geq 3$

# Why do min/plus powers give shortest paths?

For example, the third power:

(powers = min-plus)

$$\begin{aligned} A_{i,j}^3 &= (A_{i,1}^2 \odot A_{1,j}) \oplus (A_{i,2}^2 \odot A_{2,j}) \oplus (A_{i,3}^2 \odot A_{3,j}) \oplus (A_{i,4}^2 \odot A_{4,j}) \\ &= \min(\underbrace{A_{i,1}^2 + A_{1,j}}_{\text{2-leg}}, \underbrace{A_{i,2}^2 + A_{2,j}}_{\text{2-leg}}, \underbrace{A_{i,3}^2 + A_{3,j}}_{\text{1-leg}}, \underbrace{A_{i,4}^2 + A_{4,j}}_{\text{1-leg}}) \end{aligned}$$



↓  
final layover  
is 3

↘  
final layover  
is 4

## Why do min/plus powers stabilise?

1. Assume we have all loops with cost 0.

Then  $A^{\odot n}$  also calculates the lowest cost for paths of length up to  $n$ .

(0 cost loops!)

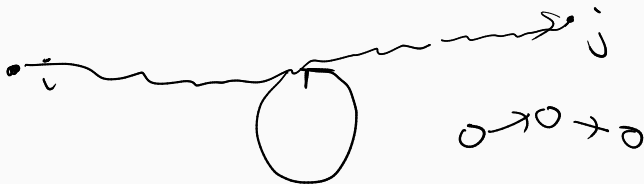
# Why do min/plus powers stabilise?

1. Assume we have all loops with cost 0.

Then  $A^{\odot n}$  also calculates the lowest cost for paths of length up to  $n$ .

2. Assume all costs are non-negative.

If we have  $N$  vertices, then the lowest cost is achieved by a path of length up to  $(N-1)$   $N=100$



# Why do min/plus powers stabilise?

1. Assume we have all loops with cost 0.

Then  $A^{\odot n}$  also calculates the lowest cost for paths of length up to  $n$ .

2. Assume all costs are non-negative.

If we have  $N$  vertices, then the lowest cost is achieved by a path of length up to  $N$ .

## Theorem

Let  $N$  be the number of vertices. If all loops are present with cost 0 and all costs are non-negative, then  $A^{\odot N} = A^{\odot(N+1)} = \dots$ .

$$\parallel \\ A^{\odot N}$$